
Poole's Specificity Revised

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Specificity of Explanations in Logic Programm.

- [Poole, 1985]: David L. Poole.
*On the Comparison of Theories:
Preferring the Most Specific Explanation.*
IJCAI9, pp. 144–147. **Binary Specificity Relation**
- [Simari & Loui, 1992]: Guillermo R. Simari, Ronald P. Loui.
*A Mathematical Treatment of Defeasible Reasoning and its
Implementation.*
Artificial Intelligence 53, pp. 125–157.
Specificity Relation is an Ordering
- [Stolzenburg & al., 2003]: Frieder Stolzenburg,
Alejandro J. García, Carlos I. Chesñevar, Guillermo R. Simari.
Computing Generalized Specificity.
J. Applied Non-Classical Logics 13, pp. 87–113.

Theory \mathfrak{L}_{II} / Derivability \vdash

A *literal* L is an atom A or a negated atom $\neg A$.

The negation symbol “ \neg ” provides an interface to the application context, but is not active in the notion of derivability.

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The theory \mathfrak{S}_Π is inductively defined to contain

- all instances of literals from Π , and
- all literals L for which there is a conjunction C of literals from \mathfrak{S}_Π such that $L \Leftarrow C$ is an instance of a rule in Π .

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- all literals L for which there is a conjunction C of literals from \mathfrak{L}_Π such that $L \Leftarrow C$ is an instance of a rule in Π .

For $\mathfrak{L} \subseteq \mathfrak{L}_\Pi$, we also write $\Pi \vdash \mathfrak{L}$.

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The set $\Pi := \Pi^F \cup \Pi^G$ is the set of *strict* rules that — contrary to the defeasible rules — are

- considered to be safe and
- not doubted in the concrete situation.

Specificity [Quasi-] Orderings on Arguments

(\mathcal{A}, L) is an *argument* if \mathcal{A} is a set of ground instances of Δ , L is a literal, and $\mathcal{A} \vdash L$.

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■ Non-Transitive Specificity Relations:

\lesssim_{P1} David Poole's original

\lesssim_{P2} Guillermo R. Simari's minor correction of \lesssim_{P1}

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■ Transitive Specificity Relations (Quasi-Orderings!):

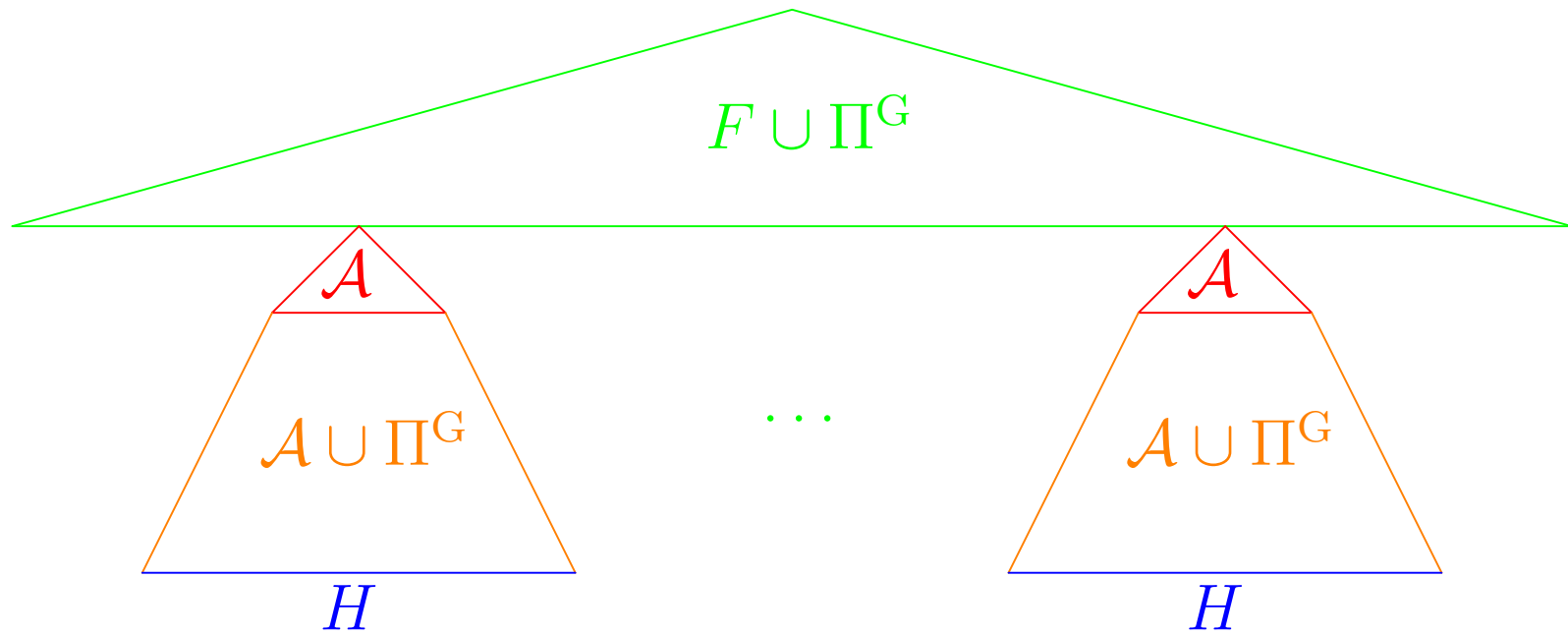
\lesssim_{CP1} Compared to \lesssim_{P3} :

– Reduction from $\mathfrak{S}_{\Pi^F \cup \Pi^G \cup \Delta}$ to $\mathfrak{S}_{\Pi^F \cup \Pi^G}$.

– Admission of Π^F after *completed* defeasible argumentations.

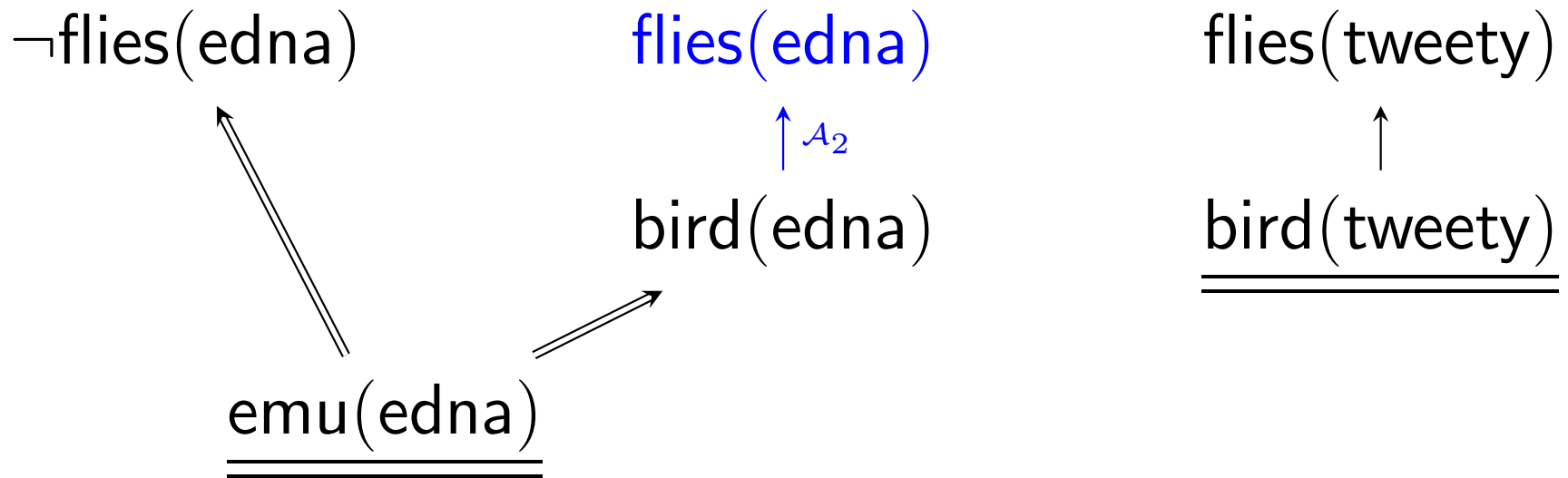
\lesssim_{CP2} Efficiency improvement of \lesssim_{CP1}

Defeasible Parts of Derivation w.r.t. (Π^F, Π^G, Δ)



	$H \subseteq \dots$	$F = \dots$
P1, P2, P3	$\mathfrak{S}_{\Pi^F \cup \Pi^G \cup \Delta}$	H
CP1, CP2	$\mathfrak{S}_{\Pi^F \cup \Pi^G}$	Π^F

Example 1 of [Poole, 1985]



$\Pi^F := \{ \text{bird}(\text{tweety}), \text{emu}(\text{edna}) \},$

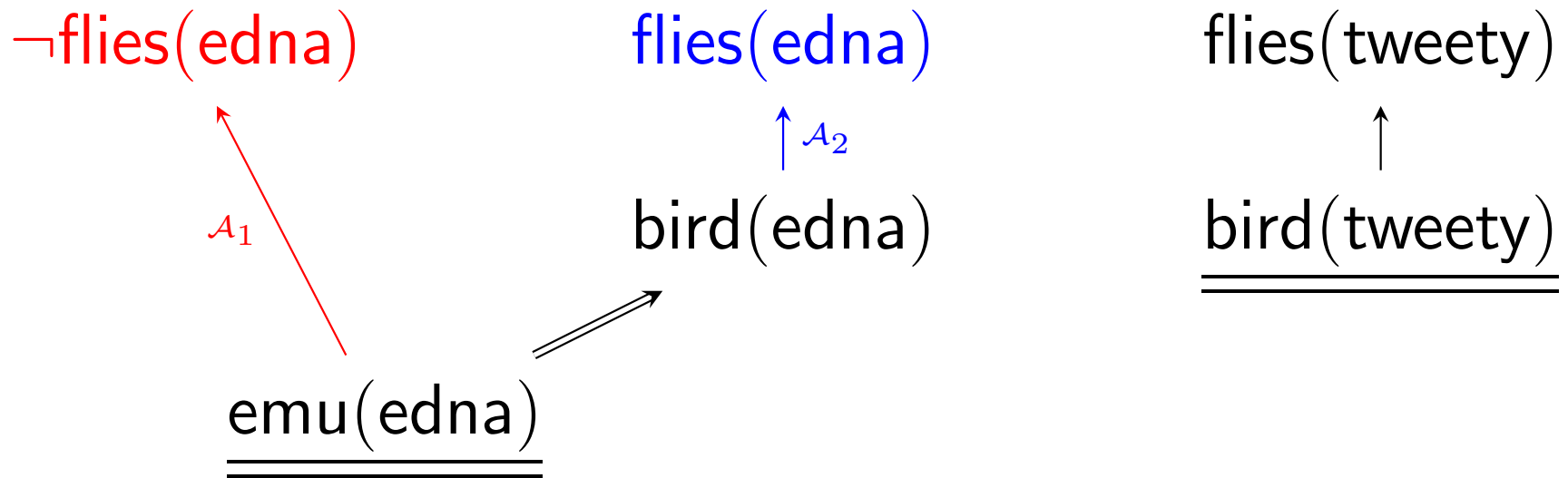
$\Pi^G := \{ \text{bird}(x) \leftarrow \text{emu}(x), \neg \text{flies}(x) \leftarrow \text{emu}(x) \},$

$\Delta := \{ \text{flies}(x) \leftarrow \text{bird}(x) \}.$

$\mathcal{A}_2 := \{ \text{flies}(\text{edna}) \leftarrow \text{bird}(\text{edna}) \}.$

$(\emptyset, \neg \text{flies}(\text{edna})) <_{P1, P2, P3, CP1, CP2} (\mathcal{A}_2, \text{flies}(\text{edna})).$

Ex.2 of [Poole,1985]. Pref. of “More Concise”



$\Pi^F := \{\text{bird}(\text{tweety}), \text{emu}(\text{edna})\}, \quad \Pi^G := \{\text{bird}(x) \Leftarrow \text{emu}(x)\},$

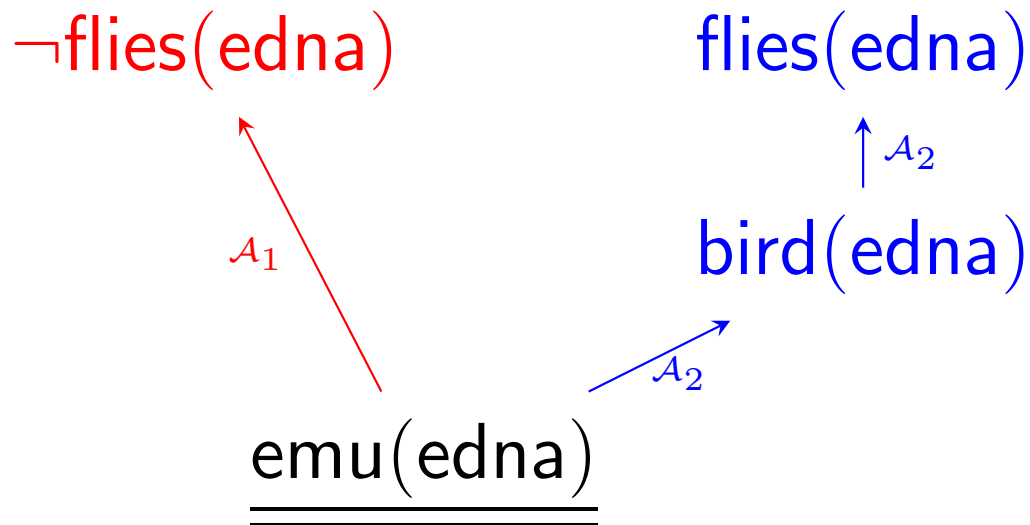
$\Delta := \{\text{flies}(x) \Leftarrow \text{bird}(x), \neg\text{flies}(x) \Leftarrow \text{emu}(x)\}.$

$\mathcal{A}_1 := \{\neg\text{flies}(\text{edna}) \Leftarrow \text{emu}(\text{edna})\}.$

$\mathcal{A}_2 := \{\text{flies}(\text{edna}) \Leftarrow \text{bird}(\text{edna})\}.$

$(\mathcal{A}_1, \neg\text{flies}(\text{edna})) <_{P1, P2, P3, CP1, CP2} (\mathcal{A}_2, \text{flies}(\text{edna})).$

Example 3 of [Poole, 1985] (renamed)



$$\Pi^F := \{\text{emu}(\text{edna})\}, \quad \Pi^G := \emptyset$$

$$\Delta := \{\text{flies}(x) \leftarrow \text{bird}(x), \neg \text{flies}(x) \leftarrow \text{emu}(x), \text{bird}(x) \leftarrow \text{emu}(x)\}.$$

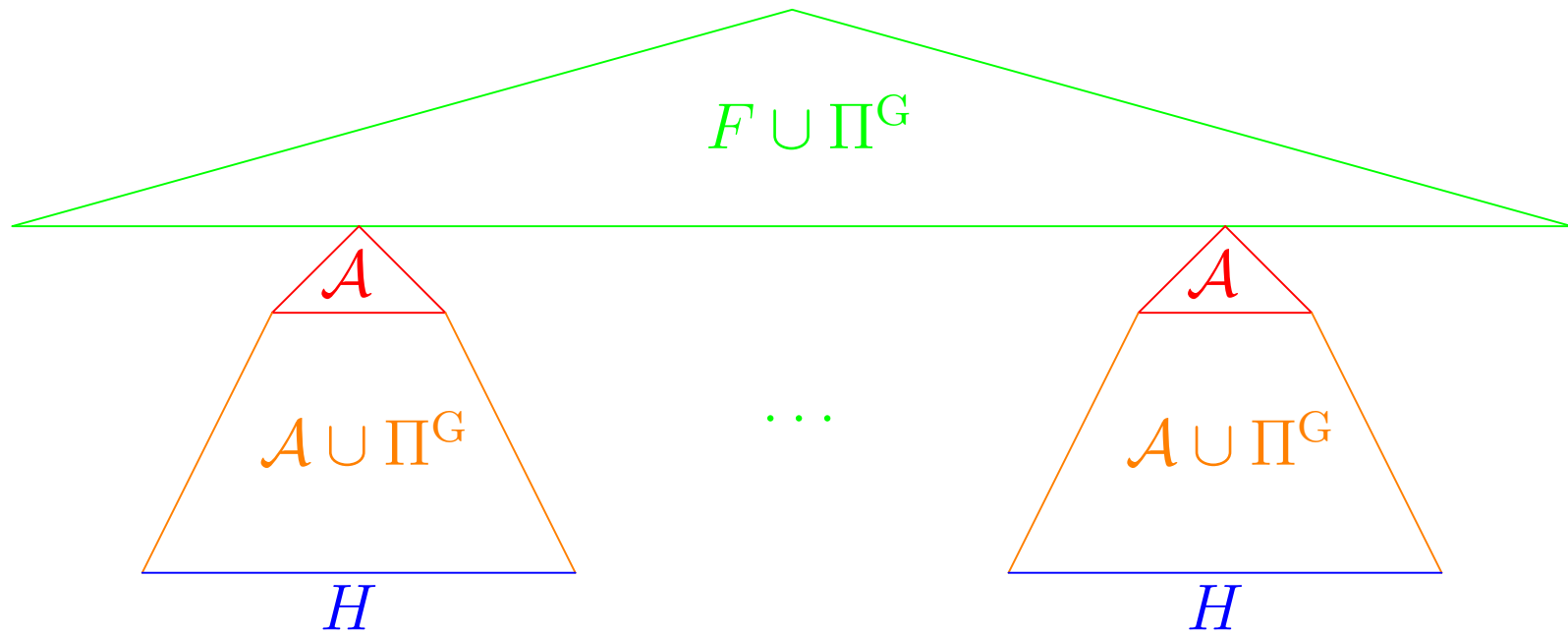
$$\mathcal{A}_1 := \{\neg \text{flies}(\text{edna}) \leftarrow \text{emu}(\text{edna})\}.$$

$$\mathcal{A}_2 := \{\text{flies}(\text{edna}) \leftarrow \text{bird}(\text{edna}), \text{bird}(\text{edna}) \leftarrow \text{emu}(\text{edna})\}.$$

$$(\mathcal{A}_1, \neg \text{flies}(\text{edna})) \approx_{\text{CP1,CP2}} (\mathcal{A}_2, \text{flies}(\text{edna})).$$

$$(\mathcal{A}_1, \neg \text{flies}(\text{edna})) <_{\text{P1,P2,P3}} (\mathcal{A}_2, \text{flies}(\text{edna})).$$

Defeasible Parts of Derivation w.r.t. (Π^F, Π^G, Δ)



	$H \subseteq \dots$	$F = \dots$
P1, P2, P3	$\mathfrak{S}_{\Pi^F \cup \Pi^G \cup \Delta}$	H
CP1, CP2	$\mathfrak{S}_{\Pi^F \cup \Pi^G}$	Π^F

Computing Specificity Relations

(phase 1) Derive the literals that provide the basis for specificity considerations. CP1/2: $\mathfrak{S}_{\Pi^F \cup \Pi^G}$. P1–3: $\mathfrak{S}_{\Pi^F \cup \Pi^G \cup \Delta}$.

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(phase 2) On the basis of

- a subset H of the literals derived in phase 1,
- the first item \mathcal{A} of a given argument (\mathcal{A}, L) , and
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we derive a further set of literals \mathfrak{L} : $H \cup \mathcal{A} \cup \Pi^G \vdash \mathfrak{L}$.

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(phase 3) On the basis of \mathfrak{L} , the literal of the argument is derived: $\mathfrak{L} \cup \Pi^F \cup \Pi^G \vdash \{L\}$.

P1–3: phase 3 is empty: $\mathfrak{L} = \{L\}$.

CP1/2: It is admitted to use the facts from Π^F in phase 3, in addition to the general rules from Π^G .

Definition [Minimal] [Simplified] Activation Set

Let \mathcal{A} be a set of ground instances of rules from Δ , and let L be a literal.

H is a *simplified activation set* for (\mathcal{A}, L) if $L \in \mathfrak{S}_{H \cup \mathcal{A} \cup \Pi^G}$.

H is an *activation set* for (\mathcal{A}, L) if, for some $\mathfrak{E} \subseteq \mathfrak{S}_{H \cup \mathcal{A} \cup \Pi^G}$, $L \in \mathfrak{S}_{\mathfrak{E} \cup \Pi^F \cup \Pi^G}$.

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H is a *minimal* [*simplified*] activation set for (\mathcal{A}, L) if

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but no proper subset of H is an [*simplified*] activation set

for (\mathcal{A}, L) .

Definitions of \lesssim_{CP1} and \lesssim_{P3}

$(\mathcal{A}_1, L_1) \lesssim_{\text{CP1}} (\mathcal{A}_2, L_2)$ if (\mathcal{A}_1, L_1) and (\mathcal{A}_2, L_2) are arguments, and we have

1. $L_1 \in \mathfrak{S}_{\Pi^F \cup \Pi^G}$ or

2. $L_2 \notin \mathfrak{S}_{\Pi^F \cup \Pi^G}$ and

every $H \subseteq \mathfrak{S}_{\Pi^F \cup \Pi^G}$ that is an [minimal] activation set for (\mathcal{A}_1, L_1) is also an activation set for (\mathcal{A}_2, L_2) .

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$(\mathcal{A}_1, L_1) \lesssim_{P3} (\mathcal{A}_2, L_2)$ if (\mathcal{A}_1, L_1) and (\mathcal{A}_2, L_2) are arguments,

$L_2 \in \mathfrak{S}_{\Pi^F \cup \Pi^G}$ implies $L_1 \in \mathfrak{S}_{\Pi^F \cup \Pi^G}$, and,

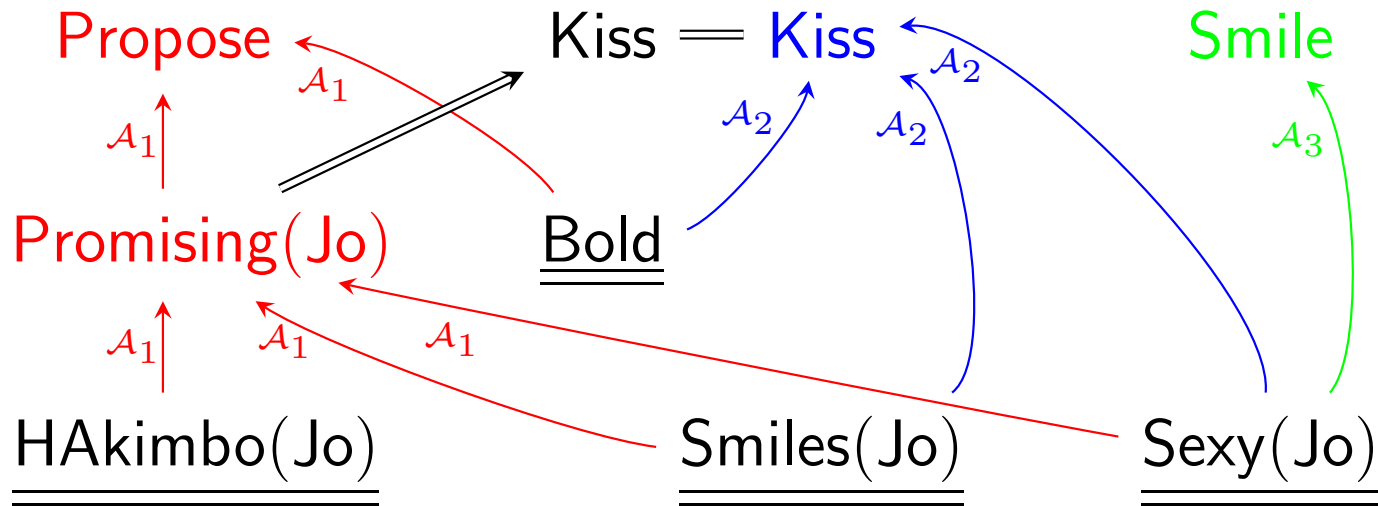
for every $H \subseteq \mathfrak{S}_{\Pi^F \cup \Pi^G \cup \Delta}$

that is a [minimal] simplified activation set for (\mathcal{A}_1, L_1)

but not a simplified activation set for (\emptyset, L_1) ,

H is also a simplified activation set for (\mathcal{A}_2, L_2) .

Example Not Transitive. Pref. of “More Precise”



$$\mathcal{A}_1 := \left\{ \begin{array}{l} \text{Promising(Jo)} \leftarrow \text{HAkimbo(Jo)} \wedge \text{Smiles(Jo)} \wedge \text{Sexy(Jo)}, \\ \text{Propose} \leftarrow \text{Promising(Jo)} \wedge \text{Bold} \end{array} \right\},$$

$$\mathcal{A}_2 := \{ \text{Kiss} \leftarrow \text{Bold} \wedge \text{Smiles(Jo)} \wedge \text{Sexy(Jo)} \},$$

$$\mathcal{A}_3 := \{ \text{Smile} \leftarrow \text{Sexy(Jo)} \}. \quad \Pi^G := \{ \text{Kiss} \Leftarrow \text{Promising(G)} \}.$$

$$\Pi^F := \{ \text{Bold}, \text{HAkimbo(Jo)}, \text{Smiles(Jo)}, \text{Sexy(Jo)} \}.$$

$$(\mathcal{A}_1, \text{Propose}) <_{\text{P1-3, CP1/2}} (\mathcal{A}_2, \text{Kiss}) <_{\text{P1-3, CP1/2}} (\mathcal{A}_3, \text{Smile}), \text{ but} \\ (\mathcal{A}_1, \text{Propose}) <_{\text{CP1/2}} (\mathcal{A}_3, \text{Smile}) \not\prec_{\text{P1-3}} (\mathcal{A}_1, \text{Propose}).$$

Conclusion: Novel Specificity Relations are . . .

- Transitive!
- Monotonic w.r.t. Conjunction!
- Even More Intuitive!
- Slightly More Efficient!
- More Comparing?

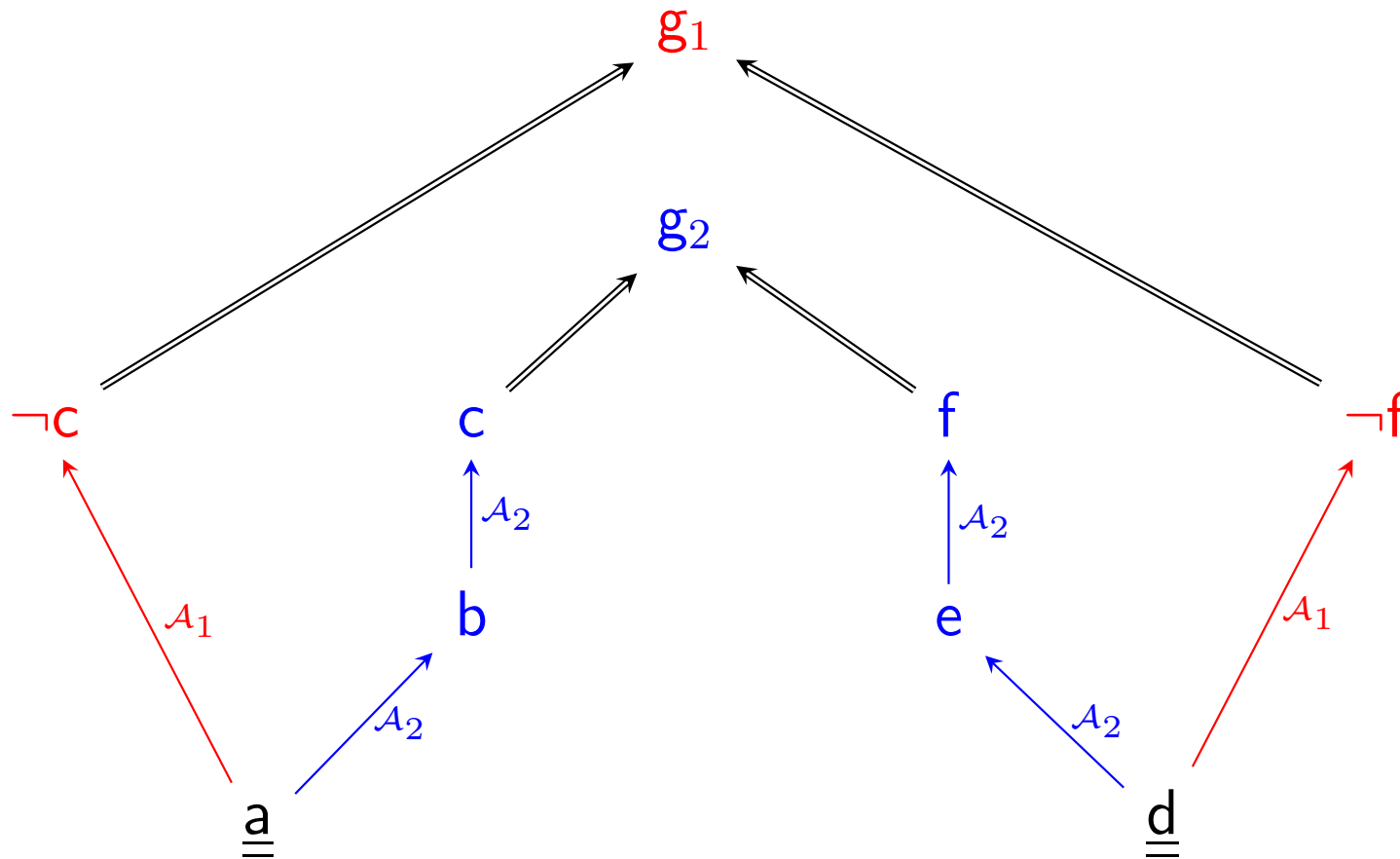
Theorem: $\lesssim_{P3} \subseteq \lesssim_{CP1}$.

Corollary: $\Delta_{CP1} \subseteq \Delta_{P3}$.

But in general: $<_{P3} \not\subseteq <_{CP1}$. Luckily!

(Otherwise monotonicity w.r.t. \wedge would be lost.)

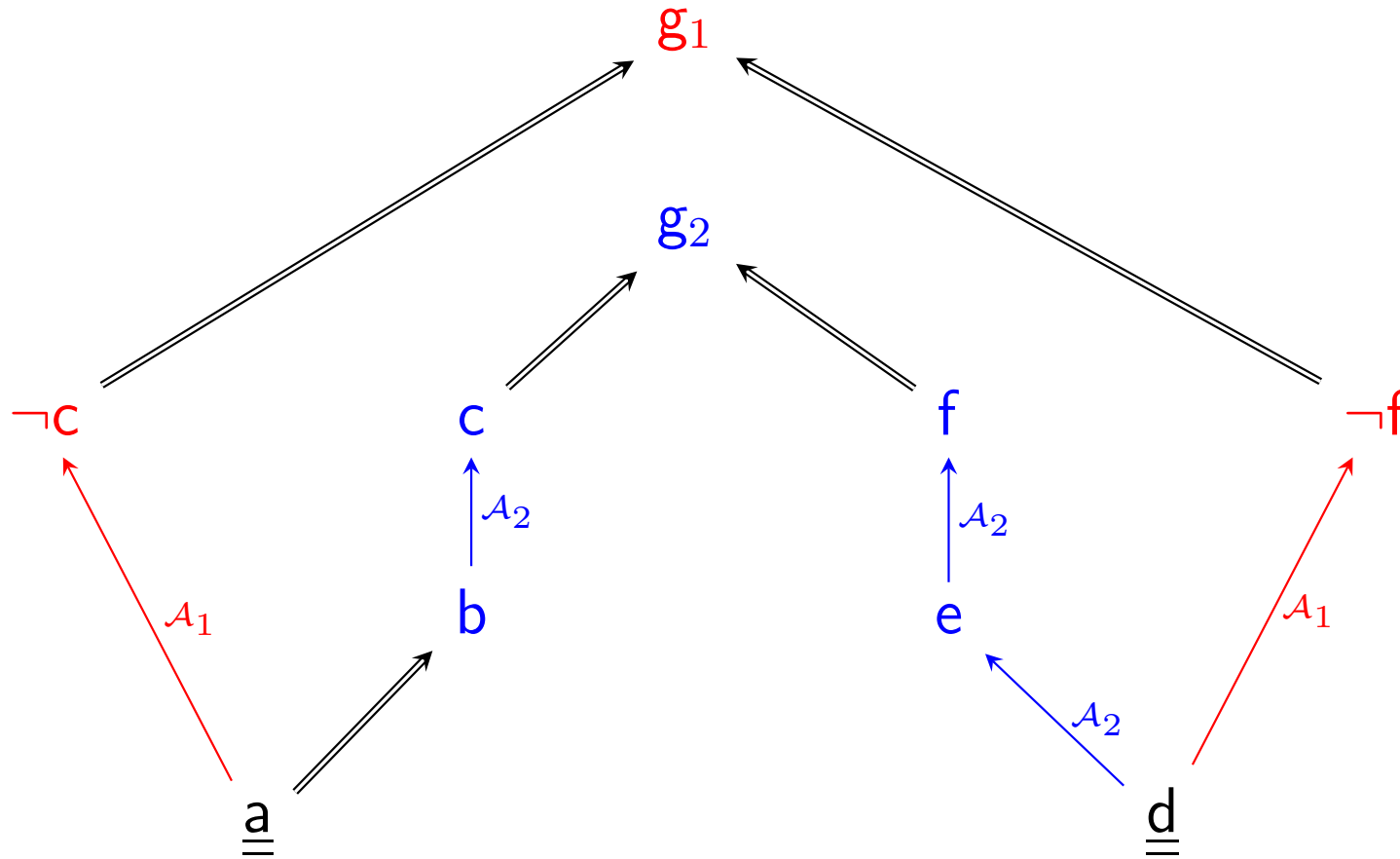
[Poole, 1985, Example 6]: Monotonicity w.r.t. \wedge



$(\mathcal{A}_1, \neg c) <_{P1-3} (\mathcal{A}_2, c)$, $(\mathcal{A}_1, \neg f) <_{P1-3} (\mathcal{A}_2, f)$, but $(\mathcal{A}_1, g_1) \Delta_{P1-3} (\mathcal{A}_2, g_2)$.

$(\mathcal{A}_1, \neg c) \approx_{CP1/2} (\mathcal{A}_2, c)$, $(\mathcal{A}_1, \neg f) \approx_{CP1/2} (\mathcal{A}_2, f)$, so $(\mathcal{A}_1, g_1) \approx_{CP1/2} (\mathcal{A}_2, g_2)$.

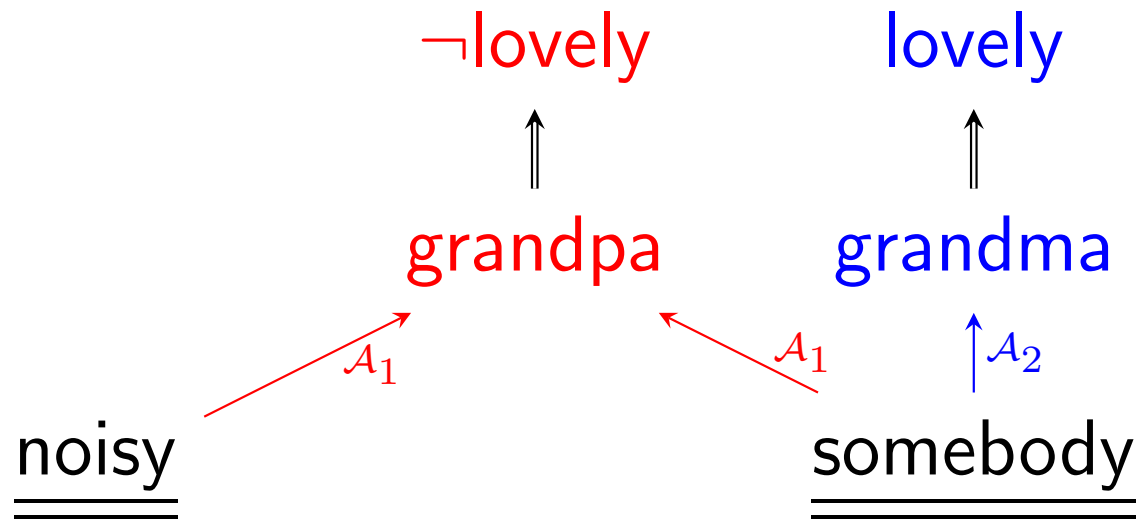
1st Variation of [Poole, 1985, Example 6]



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$(\mathcal{A}_1, \neg c) <_{CP1/2} (\mathcal{A}_2, c)$, $(\mathcal{A}_1, \neg f) \approx_{CP1/2} (\mathcal{A}_2, f)$, so $(\mathcal{A}_1, g_1) <_{CP1/2} (\mathcal{A}_2, g_2)$.

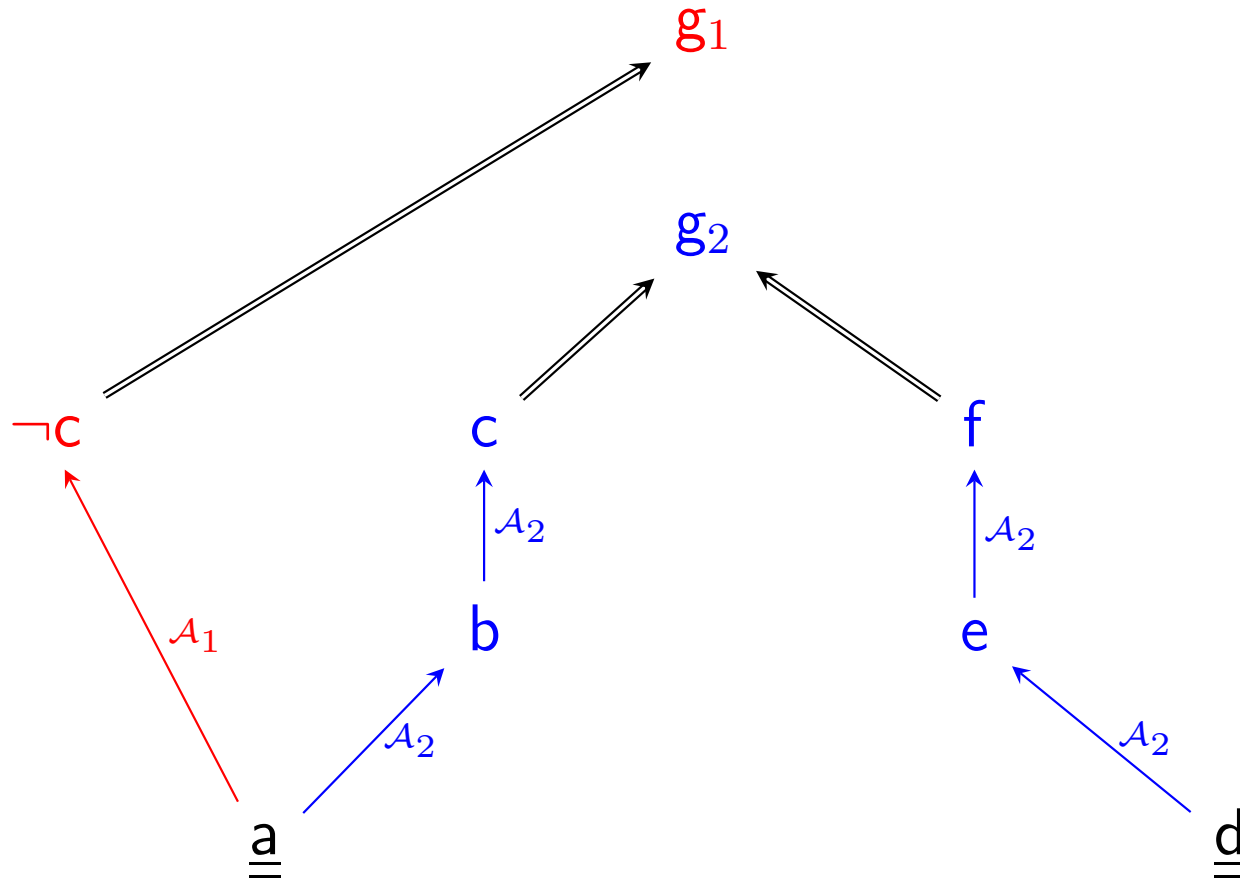
“More Precise”



$$(\mathcal{A}_1, \neg\text{lovely}) <_{\text{P1-3}} (\mathcal{A}_2, \text{lovely}).$$

$$(\mathcal{A}_1, \neg\text{lovely}) <_{\text{CP1/2}} (\mathcal{A}_2, \text{lovely}).$$

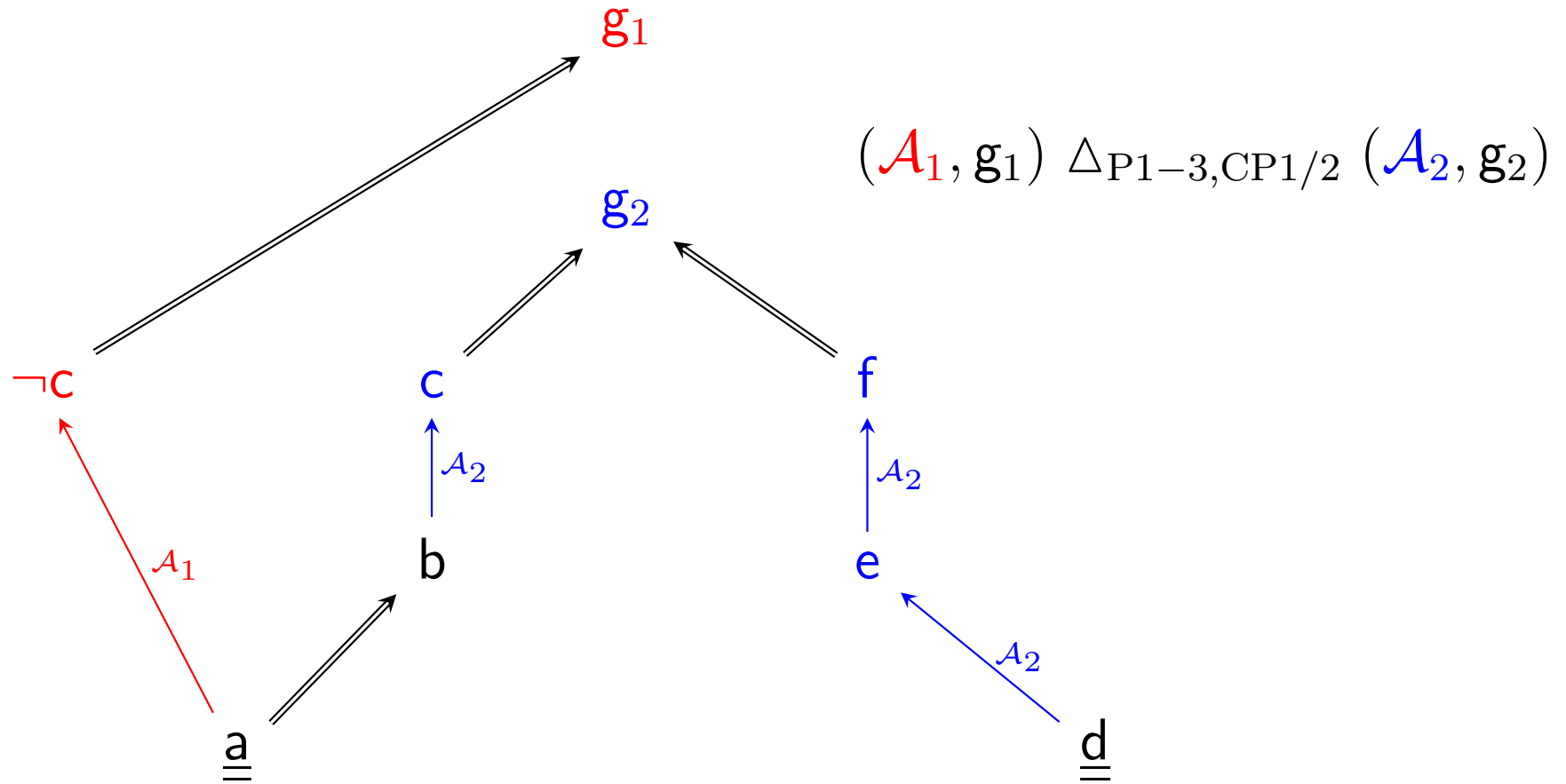
“More Precise”, 2nd Var. of [Poole, 1985, Ex. 6]



$(\mathcal{A}_1, \neg c) <_{P1-3} (\mathcal{A}_2, c)$, but $(\mathcal{A}_1, g_1) \Delta_{P1-3} (\mathcal{A}_2, g_2)$.

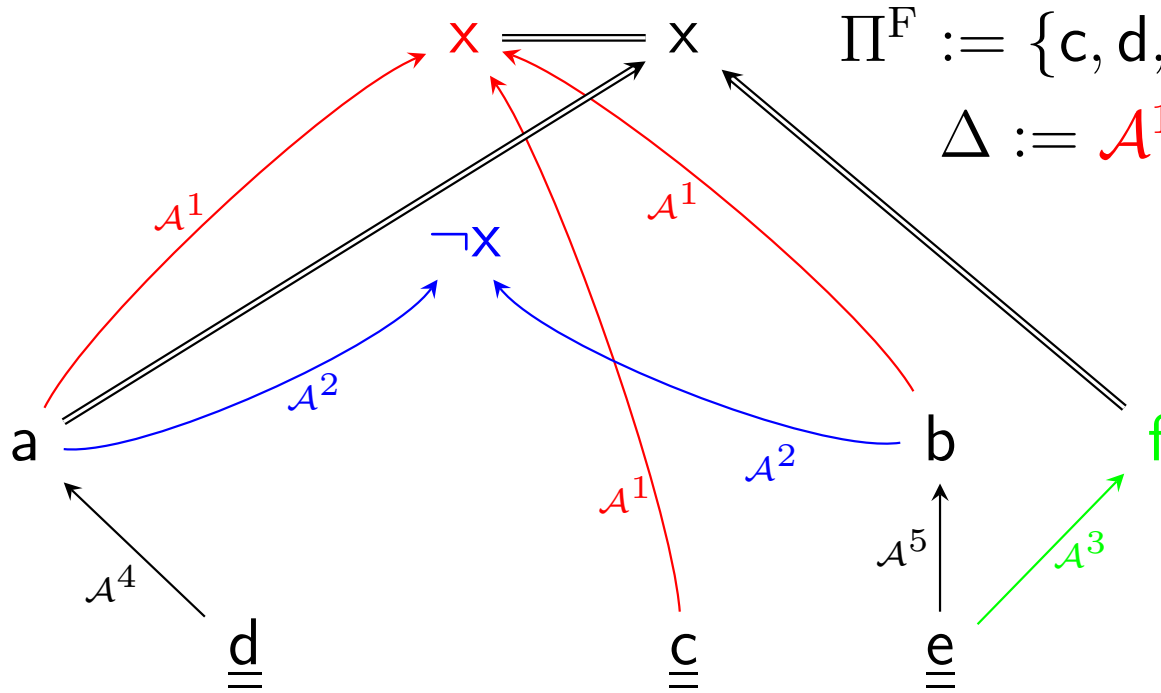
$(\mathcal{A}_1, \neg c) \approx_{CP1/2} (\mathcal{A}_2, c)$, but $(\mathcal{A}_1, g_1) >_{CP1/2} (\mathcal{A}_2, g_2)$, “more precise”.

“Precise vs. Concise”, 3rd Var. [Poole, 1985, Ex. 6]



The conflict between a being “more concise” than b and $b \wedge d$ being “more precise” than a is indeed irresolvable.

[Stolzenbg, 2003, Ex.11]: No Pruning for \lesssim_{P3} !



$$\Pi^F := \{c, d, e\}, \quad \Pi^G := \{x \leftarrow a \wedge f\},$$

$$\Delta := \mathcal{A}^1 \cup \mathcal{A}^2 \cup \mathcal{A}^3 \cup \mathcal{A}^4 \cup \mathcal{A}^5.$$

$$\mathcal{A}^1 := \{x \leftarrow a \wedge b \wedge c\}.$$

$$\mathcal{A}^2 := \{\neg x \leftarrow a \wedge b\}.$$

$$\mathcal{A}^3 := \{f \leftarrow e\}.$$

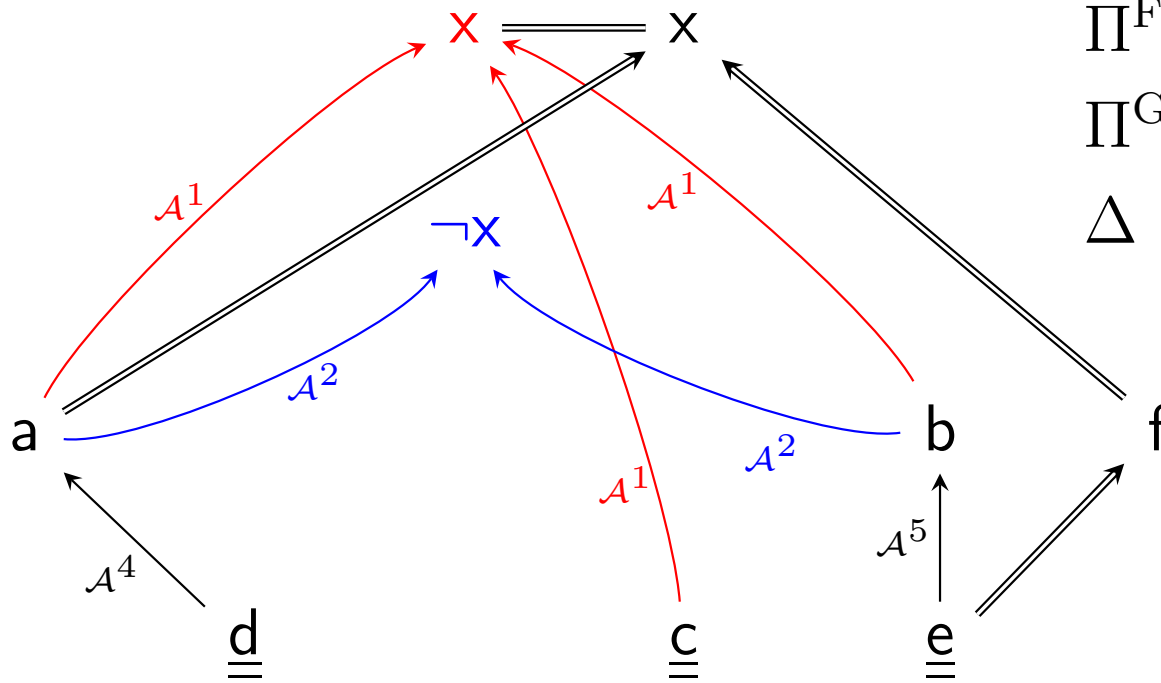
$$\mathcal{A}^4 := \{a \leftarrow d\}.$$

$$\mathcal{A}^5 := \{b \leftarrow e\}.$$

$(\mathcal{A}^1 \cup \mathcal{A}^4 \cup \mathcal{A}^5, x) <_{CP1/2} (\mathcal{A}^2 \cup \mathcal{A}^4 \cup \mathcal{A}^5, \neg x) \approx_{CP1/2} (\mathcal{A}^3 \cup \mathcal{A}^4, x)$. All \lesssim_{P1-3} -incomparable! For $(\mathcal{A}^1 \cup \mathcal{A}^4 \cup \mathcal{A}^5, x) \not\lesssim_{P3} (\mathcal{A}^2 \cup \mathcal{A}^4 \cup \mathcal{A}^5, \neg x)$

we have to consider (implicitly via $\{d, f\} \subseteq \mathfrak{S}_{\Pi^F \cup \Pi^G \cup \Delta}$) the defeasible rule of \mathcal{A}^3 , which is not part of any of the two arguments under comparison. No pruning possible for \lesssim_{P1-3} .

Variation of [Stolzenbg, 2003, Ex.11]



$$\Pi^F := \{c, d, e\},$$

$$\Pi^G := \{x \leftarrow a \wedge f, f \leftarrow e\},$$

$$\Delta := \mathcal{A}^1 \cup \mathcal{A}^2 \cup \mathcal{A}^4 \cup \mathcal{A}^5.$$

$$\mathcal{A}^1 := \{x \leftarrow a \wedge b \wedge c\}.$$

$$\mathcal{A}^2 := \{\neg x \leftarrow a \wedge b\}.$$

$$\mathcal{A}^4 := \{a \leftarrow d\}.$$

$$\mathcal{A}^5 := \{b \leftarrow e\}.$$

$$(\mathcal{A}^4, x) \approx_{\text{CP1/2}} (\mathcal{A}^1 \cup \mathcal{A}^4 \cup \mathcal{A}^5, x) >_{\text{CP1/2}} (\mathcal{A}^2 \cup \mathcal{A}^4 \cup \mathcal{A}^5, \neg x).$$

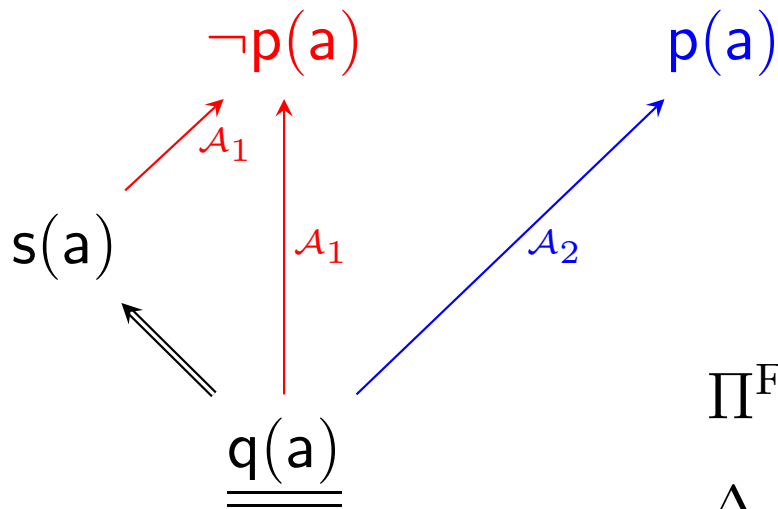
Makes sense because $d \wedge e$ is more precise (specific) than d .

$c \wedge d \wedge e$ is irrelevant because approach is model-theoretic.

$$(\mathcal{A}^4, x) <_{\text{P1-3}} (\mathcal{A}^1 \cup \mathcal{A}^4 \cup \mathcal{A}^5, x) \Delta_{\text{P1-3}} (\mathcal{A}^2 \cup \mathcal{A}^4 \cup \mathcal{A}^5, \neg x) \Delta_{\text{P1-3}} (\mathcal{A}^4, x).$$

(Bullshit!)

[Stolzenburg, 2003, Ex. p.95]: Global Effect!



$$\Pi^F := \{q(a)\}, \quad \Pi^G := \{s(x) \Leftarrow q(x)\},$$

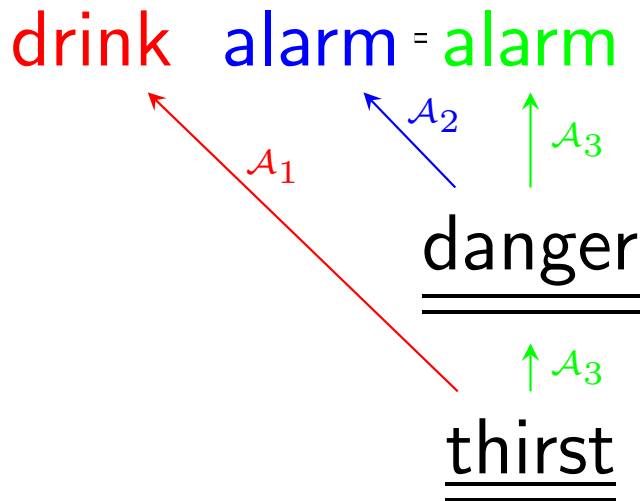
$$\Delta := \{p(x) \Leftarrow q(x), \neg p(x) \Leftarrow q(x) \wedge s(x)\}.$$

$$\mathcal{A}_1 := \{\neg p(a) \Leftarrow q(a) \wedge s(a)\}.$$

$$\mathcal{A}_2 := \{p(a) \Leftarrow q(a)\}.$$

$$(\mathcal{A}_1, \neg p(a)) \approx_{P1-3, CP1/2} (\mathcal{A}_2, p(a)).$$

\lesssim_{CP1} **vs.** \lesssim_{CP2}



$\Pi^F := \{\text{thirst, danger}\},$

$\Pi^G := \emptyset, \quad \Delta := \mathcal{A}_1 \cup \mathcal{A}_3,$

$\mathcal{A}_1 := \{\text{drink} \leftarrow \text{thirst}\},$

$\mathcal{A}_2 := \{\text{alarm} \leftarrow \text{danger}\}.$

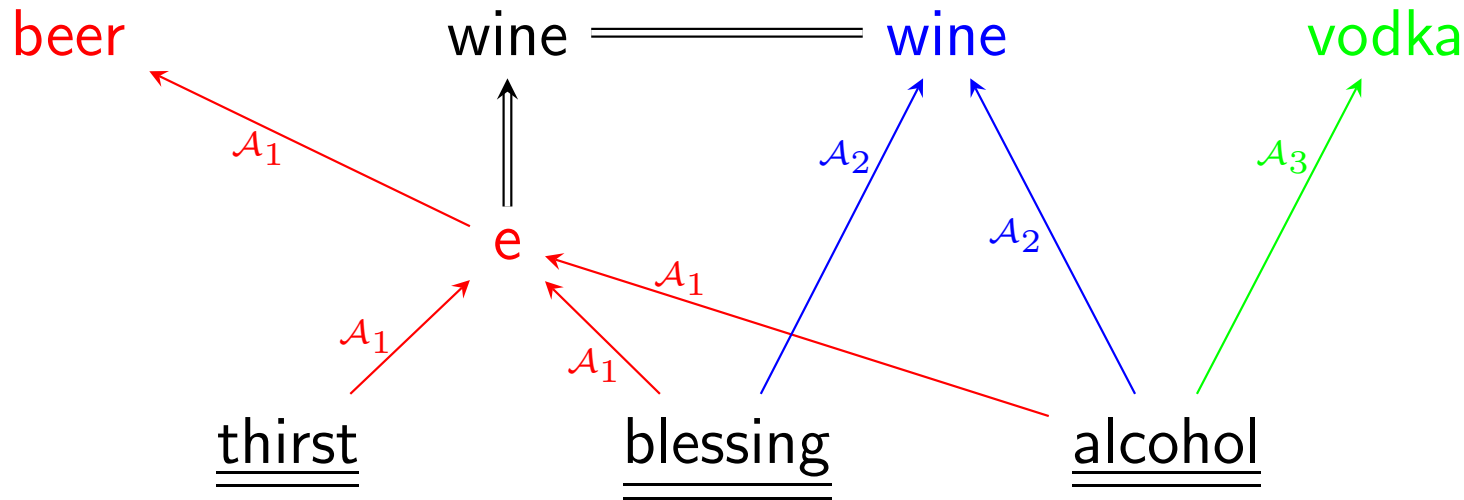
$\mathcal{A}_3 := \mathcal{A}_2 \cup \{\text{danger} \leftarrow \text{thirst}\}.$

$(\mathcal{A}_2, \text{alarm}) <_{CP1} (\mathcal{A}_3, \text{alarm}) \approx_{CP2} (\mathcal{A}_2, \text{alarm})$

$(\mathcal{A}_1, \text{drink}) <_{CP1} (\mathcal{A}_3, \text{alarm}) \Delta_{CP2} (\mathcal{A}_1, \text{drink})$

$(\mathcal{A}_1, \text{drink}) \Delta_{CP1} (\mathcal{A}_2, \text{alarm}) \Delta_{CP2} (\mathcal{A}_1, \text{drink})$

Example Not Transitive. Pref. of “More Precise”



$\mathcal{A}_1 := \{e \leftarrow \text{alcohol} \wedge \text{blessing} \wedge \text{thirst}, \text{beer} \leftarrow e\},$

$\mathcal{A}_2 := \{\text{wine} \leftarrow \text{alcohol} \wedge \text{blessing}\},$

$\mathcal{A}_3 := \{\text{vodka} \leftarrow \text{alcohol}\}, \quad \Delta := \mathcal{A}_1 \cup \mathcal{A}_2 \cup \mathcal{A}_3,$

$\Pi^F := \{\text{alcohol}, \text{blessing}, \text{thirst}\}, \quad \Pi^G := \{\text{wine} \Leftarrow e\},$

$(\mathcal{A}_1, \text{beer}) <_{P1-3, CP1/2} (\mathcal{A}_2, \text{wine}) <_{P1-3, CP1/2} (\mathcal{A}_3, \text{vodka}),$ but

$(\mathcal{A}_1, \text{beer}) <_{CP1/2} (\mathcal{A}_3, \text{vodka}) \not\prec_{P1-3} (\mathcal{A}_1, \text{beer}).$

All you need is Quasi-Ordering

A *quasi-ordering* is a reflexive transitive relation.

An (*irreflexive*) *ordering* is an irreflexive transitive relation.

A *reflexive ordering* (also called: “partial ordering”) is an anti-symmetric quasi-ordering.

An *equivalence* is a symmetric quasi-ordering.

We will use several binary relations \lesssim_N comparing arguments according to their specificity.

Corollary 0 *If \lesssim_N is a quasi-ordering, then its equivalence \approx_N is an equivalence, its ordering $<_N$ is an ordering, and its reflexive ordering \leq_N is a reflexive ordering.*

Abstract Specificity Orderings

For any relation written as \lesssim_N
 (“being more or equivalently specific w.r.t. N ”),
we define:

$\gtrsim_N := \{ (X, Y) \mid Y \lesssim_N X \}$ (“less or equivalently specific”),

$\approx_N := \lesssim_N \cap \gtrsim_N$ (“equivalently specific”),

$<_N := \lesssim_N \setminus \gtrsim_N$ (“properly more specific”),

$\leq_N := <_N \cup \{ (X, X) \mid X \text{ is an argument} \}$
 (“more specific or equal”),

$\Delta_N := \left\{ (X, Y) \mid \begin{array}{l} X, Y \text{ are arguments with} \\ X \not\lesssim_N Y \text{ and } X \not\gtrsim_N Y \end{array} \right\}$
 (“incomparable w.r.t. specificity”).

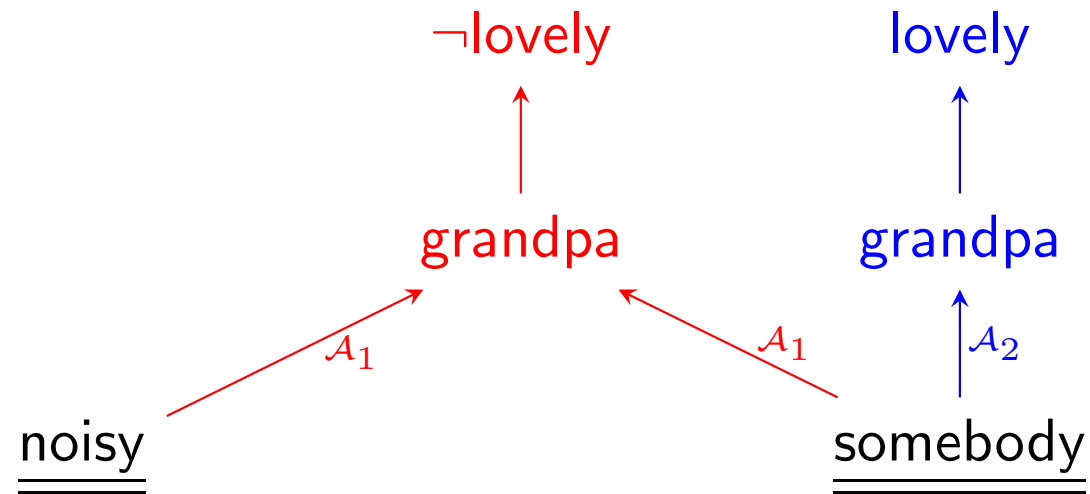
Efficiency Considerations

- Let H be a set of hypotheses. Then, roughly speaking, $(\mathcal{A}_1, L_1) \lesssim (\mathcal{A}_2, L_2)$ if every activation set H for (\mathcal{A}_1, L_1) is also one for (\mathcal{A}_2, L_2) .
- Naïve procedure enumerates possible activation sets, which is exponential in the number of possible hypothesis literals.
- Clearly, the effort for computing \lesssim_{CP1} is lower than that of \lesssim_{P3} because of $\mathfrak{S}_{\Pi} \subseteq \mathfrak{S}_{\Pi \cup \Delta}$.
- While checking \lesssim_{Px} , attention cannot be restricted to derivations which make use only of defeasible rules given in the arguments. Therefore, [Stolzenburg&al, 2003] introduce pruning derivation trees.

Path Characterization for Specificity

- $(\mathcal{A}_1, L_1) \leq (\mathcal{A}_2, L_2)$ if (\mathcal{A}_1, L_1) and (\mathcal{A}_2, L_2) are two arguments in the given specification and for each derivation tree T_1 for L_1 there is a derivation tree T_2 for L_2 such that $T_1 \trianglelefteq T_2$.
- Let T_1 and T_2 be derivation trees. Then, $T_1 \trianglelefteq T_2$ if for each $t_2 \in \text{Paths}(T_2)$ there is a path $t_1 \in \text{Paths}(T_1)$ such that $t_1 \subseteq t_2$ (omitting the root nodes).
- If the arguments involved in the comparison correspond to exactly one and-tree, then \lesssim_{P2} coincides with the path characterization (\leq and \trianglelefteq). Cf. Example 1 of [Poole, 1985].
- Two and-trees can be compared efficiently w.r.t. \trianglelefteq . It requires pairwise comparison of all nodes in the trees for each path. Hence, the respective complexity is polynomial in the size of the derivation trees.

Path vs. Argument Characterization



- Poole's specificity: $(\mathcal{A}_1, \neg\text{lovely}) <_{\text{P1-3}} (\mathcal{A}_2, \text{lovely})$
- Corrected version: $(\mathcal{A}_1, \neg\text{lovely}) <_{\text{CP1/2}} (\mathcal{A}_2, \text{lovely})$
- Path characterization: $(\mathcal{A}_1, \neg\text{lovely}) \leq (\mathcal{A}_2, \text{lovely})$
 $\left\{ \left\{ \text{noisy}, \text{grandpa} \right\}, \left\{ \text{someb.}, \text{grandpa} \right\} \right\} \quad \left\{ \left\{ \text{someb.}, \text{grandpa} \right\} \right\}$
- Argument sets: $(\mathcal{A}_1, \neg\text{lovely}) \sqsubseteq (\mathcal{A}_2, \text{lovely})$
 $\left\{ \left\{ \text{noisy}, \text{somebody} \right\}, \left\{ \text{grandpa} \right\} \right\} \quad \left\{ \left\{ \text{somebody} \right\}, \left\{ \text{grandpa} \right\} \right\}$

Back to the Arguments

- Characterization dual to \trianglelefteq based on the rules in the arguments:
- Let (\mathcal{A}_1, L_1) and (\mathcal{A}_2, L_2) be two arguments and R_i ($i = 1, 2$) be the set of (strict and defeasible) rule bodies used in the respective proofs. We define: $R_1 \sqsubseteq R_2$ if for all $r_1 \in R_1$ there exists an $r_2 \in R_2$ such that $r_2 \subseteq r_1$.
- Simplified version: Interpret \sqsubseteq simply as subset (w.r.t. complete rule sets).
- This is close to the notion *more conservative than* [Besnard&Hunter, 2001]: $\mathcal{A}_1 \subseteq \mathcal{A}_2$ and $L_2 \vdash L_1$.
- Checking \subseteq on ground literal sets can be done efficiently (NP-complete for general literals).

Further Conclusions

- Computing \lesssim_{CP_x} can be done by a modified SLD-resolution procedure, but has to enumerate all possible derivations for each query.
- Path (\trianglelefteq) and argument (\sqsubseteq) characterizations can be computed efficiently. However, they coincide with specificity notion only in special cases (e.g. no strict rules).
- Further investigation is required . . .
- Thank you very much for your attention!